

7th Groundwater Symposium of the
International Association for Hydro-Environment Engineering and Research (IAHR)

A spectral multidomain penalty method solver for the simulation of the velocity attenuation in hyporheic flows

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Abstract

A hydrodynamic model, based on a spectral multidomain penalty method (SMPM), is proposed to study the dissipation of the velocity fluctuations at the hyporheic zone. The model is based on the one dimensional Navier Stokes equations, assuming incompressibility and a hydrostatic approximation. The spatial discretization of the governing equations is done via the SMPM that is a multidomain collocation approach based on discontinuous non-overlapping subdomains that are connected by a penalty term that ensures stability of the solution by imposing weak continuity at the subdomain interfaces. The temporal discretization of the equations is handled with a high-order fractional time step technique. A spectral filter is used to stabilize the solution when spurious oscillations appear in the solution. A sinusoidal pulse is imposed at the water/sediment interface as a boundary condition, and the flow dynamics was evaluated under different conditions of kinematic viscosity. A progressive damping of the velocity fluctuations was observed in all cases, until full dissipation is reached. At that point, the flow can be governed by Darcy's law.

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Peer-review under responsibility of the Scientific Committee of the IAHR Groundwater Symposium 2014

Keyword: hyporheic zone; hydrodynamic; velocity fluctuation; numerical model; spectral multidomain penalty method

1. Introduction

The various biochemical and physical processes in the water/sediment interaction are essential for the development of vegetation and animal survival [1]. The existence of inappropriate substances from anthropogenic activities causes the death of the biota. The interstitial spaces of the sediment particles are preferential flow paths, which also is the place for the accumulation of a wide variety of macroinvertebrates [2, 3]. This species are essential for the survival of fish in the first phase of life, such as Salmon [4, 5].

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Hyporheic flow is the interaction between surface flux and subsurface flux i.e., water that is flowing in the stream channel flows into the subsurface materials of the streambed and then returns to the stream [6]. The scientific community is currently interested in the transport processes that happen in this type of flows [7]. Mathematical prediction is essential for resource management but some phenomena are ignored because analytical or computational limitations. When speaking of flow in porous media, the inertial forces are negligible compared to viscous forces. This assumption cannot represent the physical processes in turbulent rivers where nonlinear effects have to be taken into account. Various theories have been raised about the turbulence in the porous medium taking into account the scale of micro-and macro-turbulence [8, 9, 10]. Experimental tests have been designed to study turbulent phenomena associated with the velocity and pressure when the Reynolds number $Re \leq 1740$ [11, 12, 13]. Measurements of the velocity in hyporheic zone with surface turbulent flow have evidenced how the velocity fluctuations are damped by effect of the porosity [14, 15].

To the authors's knowledge, the mathematical modeling of turbulent flows in porous media has not been explored enough to be introduced into commercial codes. The nonlinear effects of the momentum equation cause errors in numerical methods of low order as finite differences or finite elements due to the numerical diffusion [16]. To solve this problem, we have explored the possibility of using high-order element based-methods (spectral), taking into account that these methods do not present problems of numerical diffusion [27]. Stefan and Higashino [17] have used the Fourier spectral method for observing the damping of a sinusoidal pulse that represent the velocity fluctuation due to turbulent processes in the sediment. However, the method uses periodic boundary conditions, situation that restricts the physical representation of the phenomenon.

Taking into account the above situation and trying to use the advantages of the methods based on elements, this paper explores the potential of the Spectral Multidomain Penalty Method (SMPM), which through a discontinuous collocation type approach allows simulating these phenomena with no periodic boundary conditions.

2. Governing equation

The starting point was the one dimensional incompressible Navier-Stokes equation (1)

$$\frac{\partial w}{\partial t} + w \frac{\partial w}{\partial z} = -\frac{1}{\rho} \frac{\partial P}{\partial z} + \nu \frac{\partial^2 w}{\partial z^2} + g \quad (1)$$

where w is the vertical component of the velocity, P is the pressure, ν is the kinematic viscosity of the water, and g is the gravitational constant. If hydrostatic flow is assumed, the pressure gradient can be represented as $\partial P / \partial z = -\rho g$. This assumption gave rise to the Burgers equation (2). From the physical point of view, the apparent kinematic viscosity ν is the parameter representing the damping capacity of the velocity w as it flows through the sediment, till reaching the point where Darcy's law applies.

$$\frac{\partial w}{\partial t} + w \frac{\partial w}{\partial z} = \nu \frac{\partial^2 w}{\partial z^2} \quad (2)$$

2.1 Boundary conditions and initial

Because the goal of the present work is to include velocity fluctuations, the boundary condition at the sediment/water interface was defined as a decomposition of a mean velocity W , and a perturbation w' given as a sinusoidal pulse (see equations (3) and (4)) [17]. The boundary condition at the bottom is given by equation (5).

$$w(0, t) = W + w' \quad (3) \quad w' = U \sin \frac{2\pi t}{T} \quad (4) \quad w(L, t) = W \quad (5)$$

In equations (3), (4) and (5), U is a characteristic velocity (pulse amplitude), usually taken as 1 cm/s, t is the time, T the period and L the sediment depth. Figure 1 shows a schematic of the physical process being modeled in this work. The upper boundary condition has the effects of turbulent flow surface. The transient layer is affected by the nonlinearity of the velocity, hence the velocities fluctuations w' are present. When the velocities fluctuations are damped by the porous medium, the velocity behaves linearly so the Darcy law can apply. The bottom boundary condition assumes that w is constant after passing completely through the transient layer, therefore its value is equal to the average velocity. It should be noted that this does not represent the total reality, since it has demonstrated with Particle Image Velocimetry (PIV) how the velocity decreases with depth in the sediment [14, 15, 18].

The initial condition was defined as $(z, 0) = W$ i.e., the porous medium preserves the laminar flow before of starting the displacement of the disturbance.

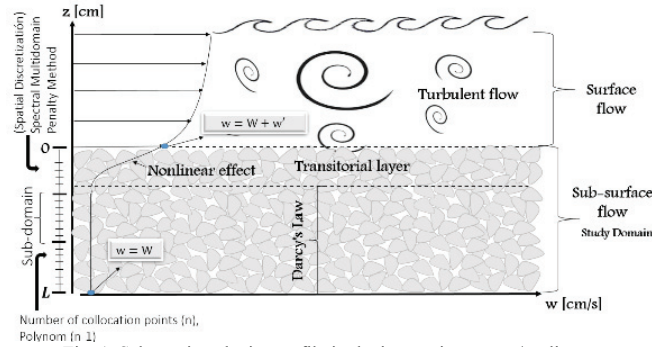


Fig. 1. Schematic velocity profile in the interaction water / sediment

2.2 Properties of the porous medium

As mentioned above, the apparent kinematic viscosity ν defines the damping of the velocity pulse caused by the turbulent flow processes at the sediment/water interface. Equation (6) presents the relationship between the kinematic viscosity ν , and porous media parameters [19, 20, 21, 22]. Equation (7) presents a more detailed definition of the variables used in (6) such as: grain size d , the medium porosity ϕ , hydraulic conductivity K and the acceleration of gravity g [23,24].

$$\nu = \frac{\phi}{K} \times \frac{gd^2}{32} \quad (6) \quad K = \frac{5.6 \times 10^{-3} \phi^3 d_s^2}{(1 - \phi)^2} \times \frac{g}{\nu_0} \quad (7) \quad \nu = \left(\frac{\nu_0}{32}\right) \left(\frac{1}{5.6 \times 10^{-3}}\right) \left(\frac{d}{d_s}\right)^2 \quad (8)$$

When replacing equation (7) into equation (6), we obtain equation (8), in which ν_0 is the kinematic viscosity for pure water and d_s is the sediment grain diameter. Figure 2 shows a plot of the porosity ϕ v.s viscosity ν for different relationship of the scale of the pores and the sediment particle diameter d/d_s . From the same figure it can be observed that there is a high viscosity when the porosity is low, i.e., the velocity slowly diffuses but is induced damping faster.

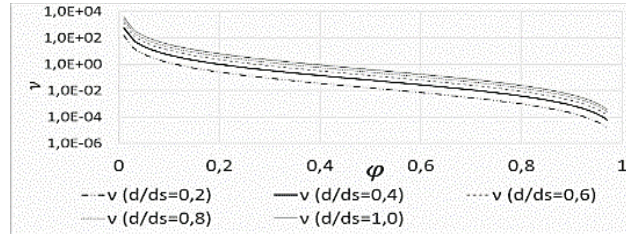


Fig. 2. Viscosity in terms of the parameters of the porous medium

3. Numerical method

3.1 Temporal discretization

In order to reduce the numerical errors introduced by the advective term, the skew-symmetric form of the nonlinear operator is used (see Equation (9))

$$\frac{\partial W}{\partial t} + \underbrace{\frac{1}{2} \left[W \cdot \frac{\partial W}{\partial z} + \frac{\partial}{\partial z} (W \cdot W) \right]}_{N(W)} = \underbrace{\nu \frac{\partial^2 W}{\partial z^2}}_{L(W)} \quad (9)$$

For the temporal discretization of the governing equation (9) a scheme of higher order fractional steps was used [25]. In this scheme the nonlinear term $N(w)$ was solved explicitly by a method of Adams-Bashforth third order and the viscous term $L(w)$ was solved implicitly by iterative solution GMRES due to not symmetrical matrix structure [9].

According to the scheme, if the equation (9) is integrated in time t_n to t_{n+1} the following semi-discrete equations decomposed into two fractional steps to w (10) (11) are obtained:

$$\frac{\hat{w} - \sum_{q=0}^{J_i-1} \alpha_q w^{n-q}}{\Delta t} = \sum_{q=0}^{J_e-1} \beta_q N(w^{n-q}) \quad (10) \quad \frac{\gamma_0 w^{n+1} - \hat{w}}{\Delta t} = v \left. \frac{\partial^2 w}{\partial t^2} \right|^{n+1} \quad (11)$$

The coefficients $\alpha_q \beta_q$ in equation (10) and γ_0 in equation (11) correspond to a third order scheme rigidly stable (SS3) [25]. Their values can be found in [25, 26].

3.2 Spatial discretization

This method is based on a collocation approach applied to multiple subdomains (elements) in one dimension. In each subdomain, any function $w(z, t)$ is approximated as

$$w(z) = \sum_{i=1}^N \bar{w}_i P_i(x) \quad (12)$$

where P_i are orthogonal polynomials (Jacobi (Legendre), periodic functions, etc.) that can be calculated hierarchically, $\bar{w}_i$ are coefficients modals or modes and N is the number of modes in the approximation.

For more details on the numerical method implementation, and the specific treatment of the advective and viscous/diffusive operator, see references [28, 29, 30, 31].

3.3 Additional stabilization strategies

Incorporation of a multidomain penalty scheme in the flow solver provides enhanced numerical stability properties that allow for simulations with higher degrees of under-resolution. However, this enhancement of numerical stability holds only in the vicinity of subdomain interfaces and physical boundaries [27]. For a higher-order polynomial discretization, additional measures need to be implemented to ensure numerical stability of the solution in the interior of a subdomain. To this end a spectral filtering [32] is applied after each fractional step (Equations (10)–(11)) in the temporal discretization. Finally, an interfacial averaging procedure [27] is applied at the subdomain interfaces. Implementation details on all three of the aforementioned procedures may be found in reference [33].

4. Setting the numerical modeling

4.1 Boundary condition and viscosity

From equations (3) and (4) were selected 2 different configurations for the boundary condition. The period T gave the characteristic velocity pulses (Figure 3). The pulses 1 and 2 had periods T in 1 s and 1.5 s respectively. Each pulse was modeled for different viscosities depending on the parameters of the porous medium (Figure 2). The Reynolds number was obtained as $Re = Ul/\nu$ where l is a characteristic length scale, which was taken to be the wave length of the pulse $l = WT$ [17], U is the characteristic velocity defined in (4), and ν is the kinematic viscosity defined by (8).

4.2 Discretization and spectral filter

For all test cases, a polynomial of degree $N=15$ was used, and a total 30 subdomains were used in the vertical direction. This configuration gave a total of 480 points of global positioning. The domain extent considered the first 100 cm from the water/sediment interaction. Finally simulations are performed for the first 150 s with a time interval of 5.072×10^{-3} s, deducted by a $CFL = 0.1$

To eliminate the numerical noise produced by the nonlinear iterations well known as the Gibbs phenomenon a spectral filter was introduced [32]. Additionally, the modeling was performed with a flexible filter.

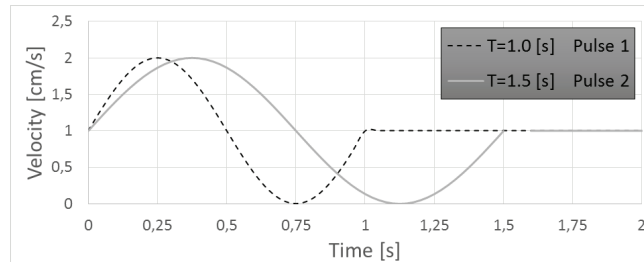


Fig. 3. Configurations of the boundary conditions at the water/sediment iteration. Amplitude $U = 1$ cm/s, average velocity $W = 1$ cm/s.

5. Numerical results

5.1 Run 1 ($T = 1.0$ s)

Pulse 1 represented lower period. In this run numerical instabilities were seen for low viscosities ($\nu \leq 0.01$ cm²/s, see figure 4a and 4b). This behavior was observed by unexpected additional oscillations at different depths (0.2 cm and 1 cm). In the same figures, it can be observed that due to the low viscosities, a fluctuation of the velocity is still detected. As expected, if the viscosity increases ($\nu \geq 0.3$ cm²/s), as in figures 4c and 4d, the dissipation of the velocity occurs in a shorter period of time. After that point the flow is governed by Darcy's law.

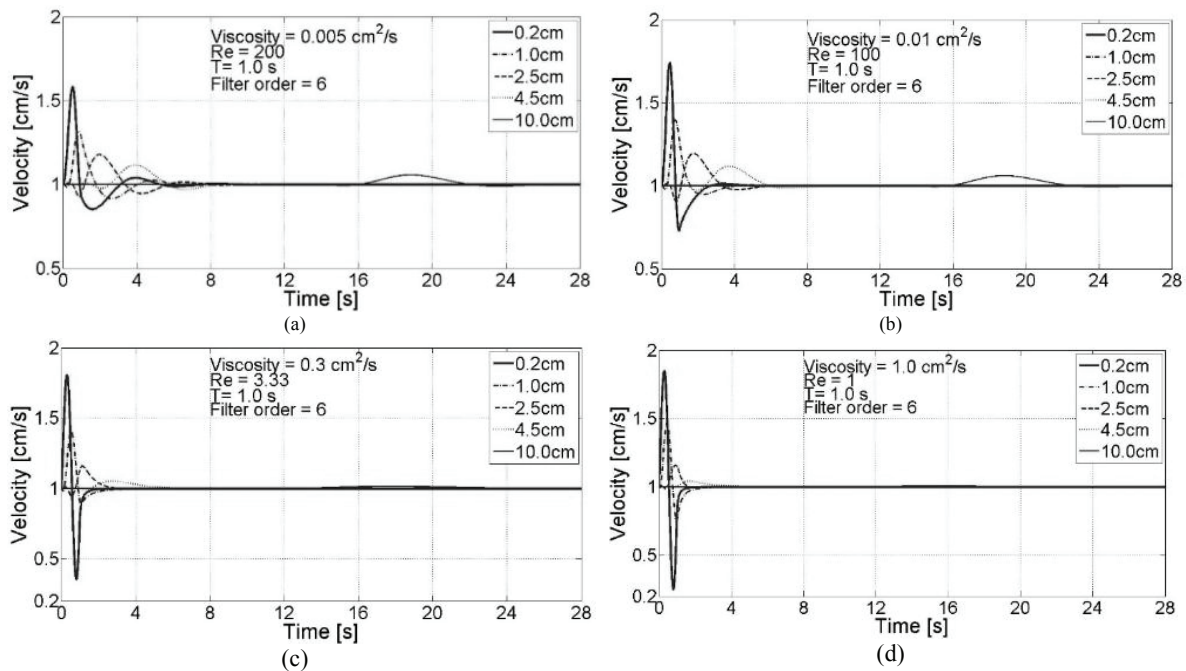


Fig. 4. Evolution of the pulse in the first 10 cm of depth in the sediment with variable viscosity and period $T = 1.0$ seconds.