



Design of an early alert system for PM_{2.5} through a stochastic method and machine learning models

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ABSTRACT

In Latin America, the levels of pollution have risen considerably in the last few years. 2019, for example, had one of the largest numbers of air quality alerts. These alerts signal an increase in respiratory diseases among the population. For this reason, this paper designs a preventive early alert system for air quality. This system compares three machine learning models and validates, through statistical and categorical parameters (9), that a stochastic model, combined with a convolution bidirectional recurrent neural network (1D-BDLM), has an accuracy of $\approx 93 \pm 4\%$ when forecasting the risk for each population group in all the monitoring stations. Likewise, it is also able to capture high pollution events without producing false alarms ($\approx 10 \pm 5\%$). This model is utilized to design an alert protocol (24 h in advance) before a pollution event occurs. The protocol distinguishes the level of alert and the type of population at risk, focusing on two objectives: pollution mitigation and risk reduction for the population. To reduce pollutant concentrations, this paper proposes limiting vehicle traffic in the most polluted city zones or, if necessary, throughout the entire area. In relation to stationary sources, this article proposes the implementation of monitoring measures in order to identify the most polluting factories and restrict their operation during a specific period of time. In regards to population risk, the protocol aims to reduce exposure time by recommending the avoidance of outdoor activities (in specific zones) and the use of protective gear, taking into consideration relevant differences between population groups.

1. Introduction

Air pollution has become a determining factor in the quality of life of highly populated and industrialized areas, as it has been associated with the emergence of respiratory diseases and an increase in public costs (Kelly et al., 2011; Maas and Grennfelt, 2016). High concentrations of particulate matter (PM), for instance, cause harmful effects on the respiratory system due to its composition and size (WHO, 2018). Hence, several countries have implemented early alert systems (EAS) for air quality, which can forecast PM concentrations. These systems have aided in the task of reducing harmful effects on human health and the government costs associated with them (airALERT, 2005; Wen et al.,

2009; Dominguez-Calle and Lozano-Báez, 2014). An important feature of the EAS is its air quality forecast focused on risk assessment, which allows an early detection of pollution, leading to a minimization of costs in public health and the coordination of meteorological and health agencies (Kumar et al., 2018).

Consequently, predictive models are the main component of the EAS: they are able to forecast pollutant concentrations in the short-term, strengthening the decision-making process during pollution events (Makowski, 2000; Longo et al., 2013; Casallas et al., 2020). Thus, in recent years, numerical models (e.g., WRF-CHEM, CAMS) (Byun and Schere, 2006; Kumar et al., 2016; González et al., 2018; Casallas et al., 2020), Machine Learning (ML) models (e.g., Artificial Neural Networks

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-ANN-, Support Vector Machines -SVM-) (Comrie, 1997; Shahraiyini and Sodoudi, 2016; Tao et al., 2019; Mogollón-Sotelo et al., 2020; Casallas et al., 2021a) and statistical approaches (Liao et al., 2021) have been used and have fostered great developments in PM predictions. Its use, in regards to air quality, generally focuses on the capability of the models to learn clear diurnal trends and their perturbations/peaks. These efforts can lead to better forecasting strategies that can be used to design, implement and evaluate air quality protocols and the model's performance (Zhang et al., 2012). Consequently, ML applications provide information on air quality through highly-precise forecasts (fine spatial and temporal resolution ≤ 24 h) that can contribute to risk management and to reduce air quality impacts on public health (Shahraiyini and Sodoudi, 2016).

Statistical analysis has been used to evaluate methodologies that increase the spatial distribution of air quality measurements. Tzanis et al. (2019) compared the Inverse Distance Weighting, three linear regression models, and the Linear Mixed Model, alongside a Feed Forward Neural Network (FFNN) model. The results highlight the effectiveness of the FFNN, as it is statistically superior when simulating the spatial variability of particulate matter. Regarding ANN, Huang and Kuo (2018) made a pioneering effort in the development of a deep Convolutional Neural Network (CNN) merged with Long Short-Term Memory (LSTM) (which they called APNet) to include air quality forecasting in smart cities, especially in terms of $PM_{2.5}$ prediction. They compared seven ML models designed with historical data (precipitation, wind speed, and $PM_{2.5}$) using four statistical parameters. Their results indicate that the APNet has the highest forecasting accuracy. For this reason, a CNN-LSTM model is a good starting point to design an ANN as a tool for risk management in a tropical city.

Beijing was one of the first cities to use models to predict air pollution (since 2007), providing air quality forecasting information to more than 100 countries. This turned the city into a forerunner in the incorporation of forecasting simulations of the Copernicus Atmosphere Monitoring Service (CAMS) (Inness et al., 2019), using the topographic and meteorological conditions of each region (WAQI, 2007). In Latin America, Brasil made the first efforts in air quality prediction, through linear models and neural networks (Lira et al., 2007). The results indicated that the analyzed simulation tools have high accuracy and can be used by the local authorities, alongside the design of a risk management program regarding air quality, such as an EAS, to reduce the risk associated with air pollution (Lira et al., 2007). Chile has also made great efforts to forecast air quality in real-time in their main cities, including forecasts using physico-chemical models, with the aim of assisting the policy-making process, to avoid severe pollution events in their cities (Saide et al., 2015). Likewise, an analysis of air quality management in Chile found that the effectiveness of $PM_{2.5}$ regulations have significantly decrease pollution and, thus, most cities have implemented an Air Quality Management Plan and applied regulations on mobile and residential sources, something that has produced positive impacts to air quality risk (Jorquera, 2021).

Colombia has also made efforts in this direction. The city of Medellín, for example, created an EAS for air quality using numerical models. Nonetheless, this alert does not consider the long-term toxic effects caused by a chronic exposure to PM or the increase in diseases associated with these pollutants (Martonen and Schroeter, 2003; Gómez Ortega et al., 2018; Baena-Salazar et al., 2019). In Bogotá, Franceschi et al. (2018) forecasted PM_{10} and $PM_{2.5}$ concentrations using an ANN, Principal Component Analysis, and k-means clustering. They managed to predict pollutant concentrations 24 h in advance, by using Multi-Layer Perceptron for the most polluted station of the city. The promising results of these studies prove that these models can be easily used for the issuance of precise early warnings with hourly forecasts in polluted areas to accurately reduce the risk.

These efforts join the increasing concern of the international community in relation to this issue, as demonstrated in the UNECE (2013) -amendment to the Gothenburg Protocol- (which entered into force in

2019): the first binding treaty with international obligations regarding levels of PM concentrations. Before this amendment, there were supra-national provisions (binding to EU countries) in the same direction, such as the directive (2008/50/EC) (Commission directive, 2015), which aims at a general reduction in PM concentrations in urban areas, and directive (2016/2284) (Commission directive, 2016), which establishes commitments to a reduction in national emissions of, among other pollutants, $PM_{2.5}$. Likewise, the WHO (2015) and UNECE (2007) have reported on the importance, costs and benefits of reducing concentrations, showing progress in the implementation of not only effective, but also economically sustainable, measures.

This article seeks to design an EAS model based on risk, stochastic and ML models that predict $PM_{2.5}$ behavior at least 24 h before an increase in concentrations. Its objective is to outline an EAS protocol, capable of being implemented in any region with an air quality monitoring network, using a general methodology that allows policy-makers to adapt it to their city, using local data (e.g., population groups, pollutant concentrations). To illustrate its possible application, the city of Bogotá, Colombia is utilized as a case study.

2. Method

2.1. Study area

Bogotá, Colombia (4.60971, -74.08175) is a city located in the tropics [where there is no framework of equations (as the geostrophic approximation) that can describe atmospheric dynamics (Holton, 2004), and local thermodynamic processes are important for the development of convective events (Casallas et al., 2021b)], in the eastern Andes Mountain range. Nevertheless, as mentioned, this design is intended to be used in any city that has an air quality monitoring network. Bogotá has 12 air quality monitoring stations, part of the Air Quality Monitoring Network of Bogotá (AQMNB), located throughout the city (Fig. 1): Guaymaral (S1) to the north, Usaquén (S2) northeast; Suba (S3) northwest; Las Ferias (S4) and Centro de Alto Rendimiento (CAR) (S5) downtown; Ministerio de Ambiente (MADS) (S6) to the east; Fontibón (S7) and Puente Aranda (S8) to the west; Kennedy (S9) and Carvajal (S10) southwest; Tunal (S11) to the south; and San Cristóbal (S12) southeast (SDA, 2020). The stations are divided into three categories: S4, S6, S7, S8, S10 are traffic-industrial stations; S1, S2, S3 are considered suburban; and S5, S9, S11, and S12 are urban background stations (Mogollón-Sotelo et al., 2020).

To determine the influence area of the stations, first, localities with only one station are represented by this sole station. However, if there are two stations within one locality, it is divided into Zonal Planning Units (ZPUs) and the closest ZPU to each station is selected. Lastly, if there are no stations in a locality, the ZPUs closest to a station are selected and integrated into its influence area.

2.2. Models

2.2.1. Deterministic models

This research evaluated 3 different models to forecast $PM_{2.5}$. Furthermore, the WRF-CHEM model Version 4.2 (Skamarock et al., 2019) was also evaluated, but due to large uncertainties (RMSE $\approx 38 \mu g m^{-3}$) produced by Bogotá's emission inventory (e.g., Kumar et al., 2016; Casallas et al., 2020; Ballesteros-González et al., 2020), it could not be fully validated for the EAS. Although the behavior of wind field, radiation, temperature, and precipitation are well represented, as identified by several authors (e.g., Kumar et al., 2016; Casallas et al., 2020; Guevara-Luna et al., 2020; Ballesteros-González et al., 2020), the pollutants have large uncertainties in their magnitudes. For this reason, it is important to make major efforts in order to develop a reliable emission inventory database for the city of Bogotá, which would allow the incorporation of this model to the EAS, bearing in mind that the

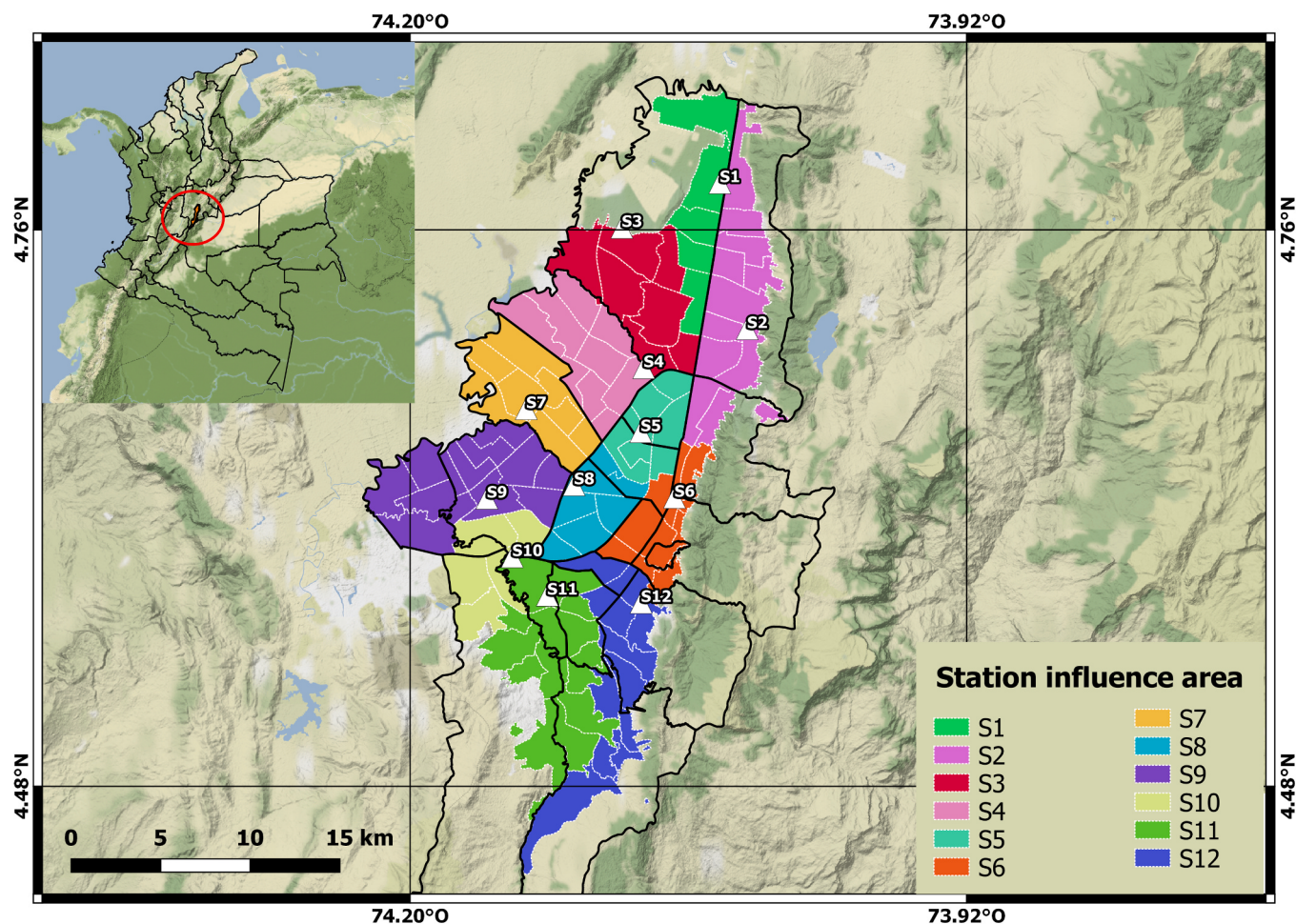


Fig. 1. Geographical location and influence area of the 12 stations (white triangles) of the AQMN. The polygons indicate the division into localities (black borders) and the division into ZPUs (white borders) in the city of Bogotá.

WRF-CHEM model has proven to be useful in the comprehension of the fundamental behavior of contaminants and their sources, and in the evaluation of different air quality scenarios. For example, [Sokhi et al. \(2021\)](#) showed that understanding the behavior of pollutants (e.g., ozone), especially in low pollution conditions, is important because some contaminants can increase their concentrations in an undesired manner, something that must be accounted for when developing new policies.

Three different ML models were evaluated. The first model was the SVM model, created by [Cortes and Vapnik \(1995\)](#). This machine aims at orienting a hyperplane in a way that is the farthest possible from each data of the series, something that allows it to classify the data and make regressions with a classification function ([Fletcher, 2009](#)). For this reason, this tool has been used in air pollutant predictions (e.g., [Lu and Wang, 2005](#); [Hou et al., 2014](#); [Mogollón-Sotelo et al., 2020](#)), delivering satisfactory results in regards to describing $PM_{2.5}$ behavior and magnitude. On the other hand, ANN were published for the first time by [Ivakhnenko and Lapa \(1965\)](#) and improved by [Ivakhnenko et al. \(1967\)](#). These networks are used to recognize images, to determine the precipitation of a day and to describe the behavior of a pollutant, among others (e.g., [Hochreiter and Schmidhuber, 1997](#); [Zhang et al., 2012](#); [Shahraiyini and Sodoudi, 2016](#)). As the accuracy of these techniques has been widely tested (e.g., [Huang and Kuo, 2018](#); [Franceschi et al., 2018](#); [Tzanis et al., 2019](#)) for air quality modeling, we evaluated their precision to simulate $PM_{2.5}$ in a high-altitude tropical city and their capacity to work as an input tool for an EAS.

To build the training sets, air quality hourly data from 12 stations of

the AQMN, with at least 70000 data points per station between 2015 and 2020, were used. In the cases where the data had missing values, they were imputed using the hourly mean of each station. Although not shown here, an imputation using linear regressions/dense neural networks, taking into account the closest station with available data, was performed for the station S10. However, the simulation results did not show considerable changes when following this procedure. Thus, the hourly mean imputation method was used, as it needs less computational resources. The X-vector (Input) and Y-vector (Output) are constructed equally for each model, the X-vector is designed with slices of 120 data points previous to the “present” time, and the Y-vector has 24 data points that represent 24 h in the “future”. This way, 120 data points (hours) from the “past” produce the simulation of 24 h in the “future” (See [Fig. 2](#) and the [Supplementary Material](#) -hereafter SM- Table SM1). For the three models, a grid search method (e.g., [Ndiaye et al., 2019](#)) was performed to select the parameters that produce the best forecast (Table SM1). Additionally, an early stopping method is applied to the ANNs to prevent them from overfitting (e.g., [Prechelt, 1998](#)).

Here the SVM is built following the work of [Mogollón-Sotelo et al. \(2020\)](#). Nevertheless, it is important to acknowledge that this model has a limitation in comparison to the other two ML techniques: the forecast produces one value at a time, so the 24 h simulation has to use predicted values, something that increases the uncertainty with respect to the neural networks (for more details, see [Mogollón-Sotelo et al., 2020](#)). The LSTM network is based on ([Casallas et al., 2021a](#)), while the design of a 1-Dimension CNN merge with a bidirectional LSTM (hereafter 1D-BDLM) is based on [Huang and Kuo \(2018\)](#). However, the structure

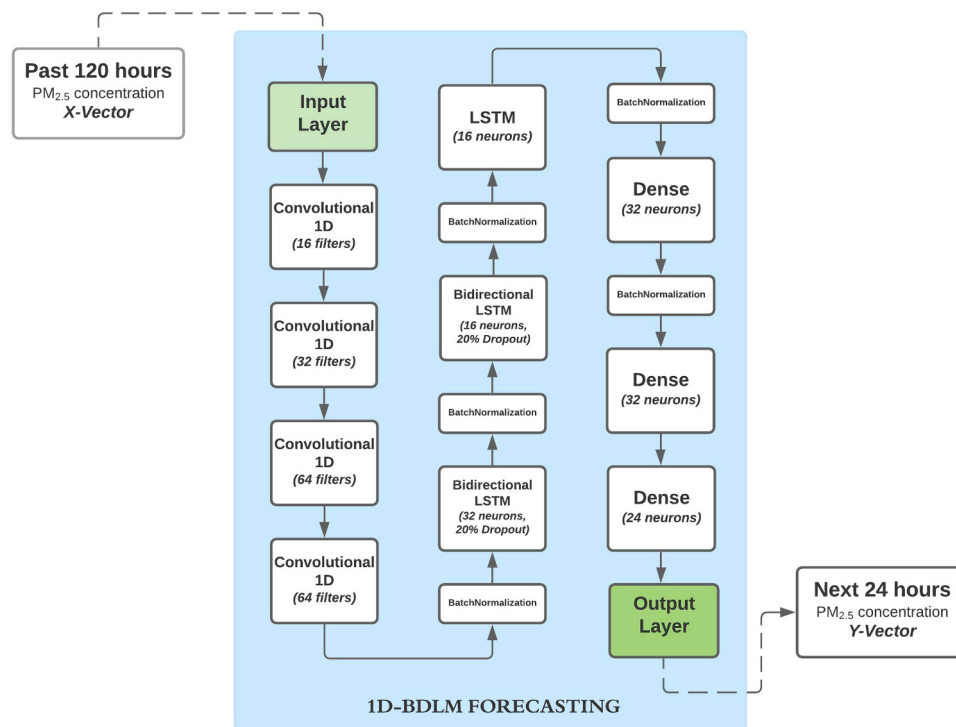


Fig. 2. 1D-BDLM neural network structure. Notice that every box has the number of neurons/filters in the layer and that the dropout percentage of a layer is also indicated.

and layers of the latter are modified to achieve the objective of forecasting 24 h as output (instead of one, as in Huang and Kao's case). The structure of the neural network models are described in Fig. 2 (1D-BDLM) and in Figure SM1 (LSTM), and the parameters of the three ML models are shown in Table SM1. The SVM was designed with SK-learn-0.24.1 (Pedregosa et al., 2011) and the ANNs were designed using Tensorflow-2.4.1 (Abadi et al., 2015) and Keras-2.4.3 (Chollet et al., 2015) libraries from Python-3.8.

2.2.2. Stochastic model

The Monte Carlo model (Eq. 1) includes the uncertainty present in every input data supplied by the AQMNB, through variables of a continuous distribution of $PM_{2.5}$ concentrations. This allows the calculation of probabilistic risk for each population group of the selected stations. This was conducted to include the uncertainty of the input data and the effects of atypical data on the model's results and evaluation, something not included in the deterministic risk (Asante-Duah, 2017; McFarland and DeCarlo, 2020). In relation to most environmental problems, this differential and gender-based probabilistic approach is required to specify the spectrum of available information, which may contribute to the quality of the risk assessment task for each population group, and to simultaneously provide decision-makers with a robust analysis (Bu et al., 2019). To design this model, we identified the best data distribution adjustment for daily $PM_{2.5}$ concentrations from January 1st, 2018 to December 31st, 2020, in each station of the AQMNB. Different probabilistic distributions are used (c.f. Table SM2) as the main input of the Monte Carlo model (Liu et al., 2020a).

$$E(\chi) \approx \frac{1}{N} \sum_{n=1}^N \chi_n \quad (1)$$

Eq. 1. Monte Carlo model. Where $E(\chi)$ is the expected value, χ is a random variable and N is the size of the sample.

2.3. Risk Assessment for $PM_{2.5}$ in Bogotá

The city of Bogotá implemented a corrective air quality alert system

(Decreto 595 of, 2015), i.e., actions to mitigate population exposure, executed after a pollution event has occurred. For this reason, the protocol must be improved by designing an EAS that can be activated 24 h prior to the pollution event. To achieve this, the risk of acute exposure to $PM_{2.5}$ is assessed, based on the negative effects on health (Xing et al., 2016). Thus, the method of risk assessment of the EPA (2020) was incorporated. This method is divided into three phases: 1. Identification and characterization of the danger; 2. Characterization of the risk; and 3. Risk management.

2.3.1. Identification and characterization of the danger

In this phase, the danger was identified based on the yearly maximum permitted level of $PM_{2.5}$, internationally suggested by the WHO, of $10 \mu g m^{-3} year^{-1}$ (hereafter WHOYL) (WHO, 2018). We also identified the percentage of days that surpassed the WHO's daily limit of $25 \mu g m^{-3} day^{-1}$ (hereafter WHODL) (WHO, 2018), and hourly composites are used to evaluate the hourly behavior of the pollutant and the risk associated with it. On the other hand, the Air Quality Index (AQI) is used, instead of Bogotá's Air Quality Index (BOAQI), as the former has been used internationally and, thus, can be utilized for any city. Once the risk is identified, PM exposure of the population can be assessed.

2.3.2. Characterization of the risk

The population of the studied zone (data from (DANE, 2018)) is classified into 5 subgroups: Infants (< 3 years), Children (3–11 years), Young people (12–29 years), Adults (30–65 years), and Older people (> 65 years). Furthermore, the last three groups are subdivided by gender. This selection of reference groups allows the EAS to mitigate the risk of developing diseases related to $PM_{2.5}$ pollution in the entire population, through a differential approach (e.g., Wang et al., 2018; Lu et al., 2019; Gómez Peláez et al., 2020). To determine the risk for each population group, deterministic models coupled with a probabilistic model are used. These models, incorporated to the EAS, allow highly precise decision-making, in relation to risk management, in a preventive manner, instead of a corrective one (Liu et al., 2020b). Hence, this phase

quantitatively determines the probability of harmful effects occurring due to PM_{2.5} exposure for the entire population.

To quantitatively determine the population risk in relation to health, the methodology of [Greene and Morris \(2006\)](#), based on the [EPA \(2014\)](#), is used. With it, we can determine that non-carcinogenic population risk (R_p) (Eq. 2) depends on C (PM_{2.5} concentrations in μgm^{-3}) and UR , where UR becomes the percentage (c.f. Table SM3) of each population group of the studied zone. From Eqs. 1 and 2, we can derive Eq. 3, which implements the Monte Carlo model to stochastically predict population risk. With the determined model and distributions, 200000 random simulations are conducted to represent possible risk scenarios ([Asante-Duah, 2017](#)), obtaining the differential and gender-based risk, using a confidence interval of 95%.

$$R_p = C * UR \quad (2)$$

Eq. 2. Population Risk (R_p)(%)

$$R = \frac{1}{N} \left(\sum_{i=1}^N C_i * UR \right) \quad (3)$$

Eq. 3. Adaptation of the Monte Carlo equation to calculate population risk. Where C_i is the random variable of concentration for each of the i experiments and N is the number of experiments.

2.4. Statistical validation of the models

For the evaluation of the model, we used 182 days that are removed from the training set. These days were distributed in different AQI categories so that the model was capable of reproducing low, medium, and high air pollution scenarios. In addition, every month of the year has at least 10 days of representation (not continuous days, and taking week-end and week days to also account for weekly changes), in order to evaluate the different rainy seasons and also a variety of weather conditions (e.g., wind field, precipitation). To validate the model, we used the Root Mean Square Error (RMSE), the Mean Bias (MB), the R^2 , the Index Of Agreement (IOA), the Factor of Two (FAC2), the Normalized Mean Bias (NMB) as statistical parameters (e.g., [Willmott et al., 1985](#); [Barnston, 1992](#); [Boylan and Russell, 2006](#); [Cobourn, 2010](#); [Tzanis et al., 2019](#); [Mogollón-Sotelo et al., 2020](#); [Liao et al., 2021](#)). As categorical statistics, the Hit rate (HIT), the False Alarm Rate (FAR) and the Proportion of Correctness (POC) were used (e.g., [Chai et al., 2013](#); [Sayeed et al., 2021](#)). A further explanation of these parameters, including its equations, are found in Table SM4.

2.5. Risk management

Based on the examination of the monitoring information, the simulations and the risk calculations, the current District Protocol for the Response to Air Pollution Alerts in Bogotá (2015) and several international protocols (e.g., [Liu et al., 2020b](#)) are analyzed, in order to articulate and incorporate immediate responses and adequate management measures to minimize exposure and vulnerability. The technological tools articulated with preventive risk management may help state agencies to decrease PM concentrations and to avoid yellow or orange alert events. Likewise, measures related to actions and communication with the general public are incorporated, in order to improve their response and self-management concerning the risk of exposure to high concentrations of PM.

3. Results and discussion

3.1. Identification and characterization of the risk

To identify the risk in the studied zone, we performed three different evaluation criteria (Fig. 3). First, the PM_{2.5} hourly mean was calculated (Fig. 3a), showing that in the case of Bogotá there are two local

maximums in the day: the first one between 6 h and 8 h Colombian Local Time (CLT) and the second one between 18 h and 20 h CLT. These slots reflect the times when traffic sources are more present, taking into account that people are moving from and to work ([Castillo-Camacho et al., 2020](#)). The WHO does not have a limit for an hourly value. Indeed, when using the WHODL, at least 9 of the 12 stations surpass it for a few hours, something that must be addressed in air quality policies. In addition, a daily evaluation of PM_{2.5} concentrations shows that, between 2015 and 2020, all the stations surpassed the WHODL (blue bars in Fig. 3b) at least 10% of the days. In S8, S9, S10, S11, this limit is surpassed in $\approx 20\%$ of the days and, in S9/S10 the limit is crossed more than 40/70% of the days, respectively.

On the other hand, in 2020 all the stations had higher yearly mean concentrations (orange bars Fig. 3b) than the WHOYL. This situation happened even during the COVID-19 pandemic, where most of the pollutants decreased their concentrations due to the lack of mobility and a drop in industrial activities ([Sokhi et al., 2021](#)). Likewise, it is important to mention that, i) as seen in Fig. 3b, stations S8, S9, and S10, located in the southwestern area of the city, have concentrations 2 or 3 times higher than what the WHO provides. This is because this zone has the greatest number of industries and diesel-based public transport (e.g., [Rojas, 2004](#); [Castillo-Camacho et al., 2020](#)) (see the method section for more details about the type of stations). ii) Colombia, especially Bogotá, suffers from Long Range Transport (LRT) such as biomass burning (wildfires) coming from the East and Southeast part of the country (e.g., [Ballesteros-González et al., 2020](#); [Mendez-Espinosa et al., 2020](#); [Sokhi et al., 2021](#)). These arguments lead to the conclusion that there is a risk to public health in the city in an hourly, daily, and yearly time resolution, especially in the southwestern polygon.

3.2. Exposure and risk assessment

To determine which tool has the highest precision when forecasting PM_{2.5}, the performance of the models (SVM, LSTM, and 1D-BDLM) is compared by simulating 182 days that are selected as described in Section 2.4. These days are evaluated by means of 9 statistical parameters for each station (Fig. 4 and details in Table SM2). Fig. 4 shows the comparison of three ML models using evaluation parameters, where the HIT, the FAR, and the POC are categorical parameters and their threshold is the WHODL. The parameters are calculated for the daily mean of each station and the mean station type (i.e., Industrial-Traffic Mean, Suburban Mean, and Urban-Background Mean), that is found using a virtual station: an hourly mean composite of the stations in the same category is calculated for the model's results and observations, and then the statistics are computed.

For all the parameters, except the HIT and the NMB, the 1D-BDLM has the best performance and the SVM the worst. The SVM has the lowest scores, mainly due to overestimations of PM_{2.5} concentrations. This is probably caused by their inability to grasp vastly fast changes ([Mogollón-Sotelo et al., 2020](#)) and the pollutant's behavior, as seen in the R^2 values. In spite of this, the precision of the SVM is better than the ones presented in previous studies of Bogotá (e.g., [Zarate et al., 2007](#); [Kumar et al., 2016](#); [Casallas et al., 2020](#); [Pulido et al., 2020](#); [Ballesteros-González et al., 2020](#)). The 1D-BDLM and the LSTM models have good performance when predicting PM_{2.5} and can be used as an input for the EAS system. Although, in the HIT parameter, the two networks have similar performances, for the other statistics, the 1D-BDLM has better results (except for NMB and MB where they are very close, but the LSTM is better, due to the consistency of the results throughout the stations), possibly due to the CNN's capability of identifying key features, and also because the bidirectional LSTM has the ability to learn more robustly and produce nowcasting's (e.g., [Huang and Kuo, 2018](#); [Sayeed et al., 2021](#)). For this reason, this 1D-BDLM network is chosen to be further described and analyzed.

The 1D-BDLM model presents values higher than 0.6, 0.85, and 95% for the R^2 , IOA, and FAC2, respectively. This indicates that the model is

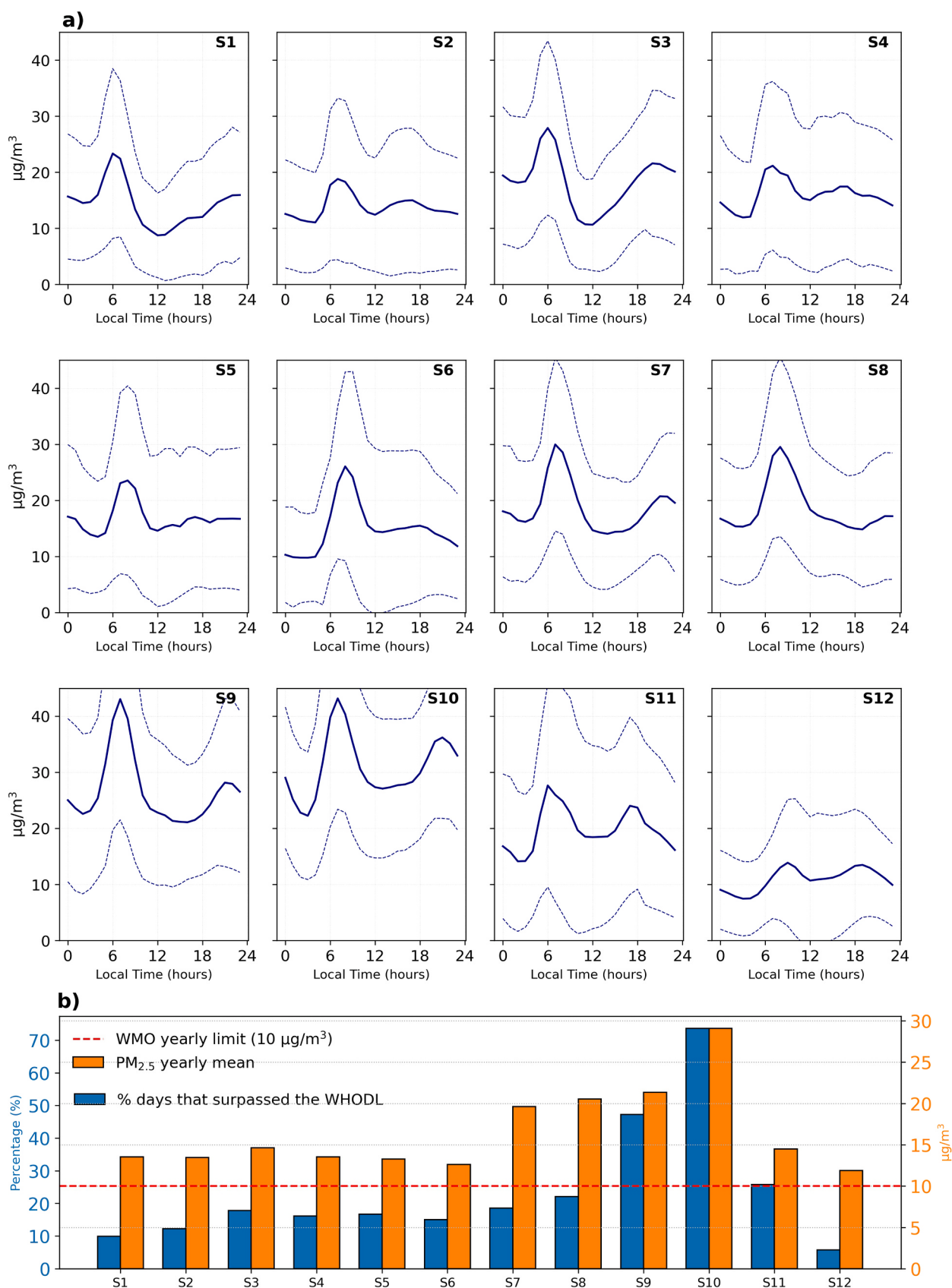


Fig. 3. a) PM_{2.5} hourly mean concentration for every station calculated for the period between 2015 and 2020. The dotted lines represent the standard deviation, to account for the data variability. b) The blue bars represent the percentage of days that surpassed the WHODL, per station. The orange bars show the PM_{2.5} yearly mean concentration of 2020 per station. Notice that the red dashed line is the WHOYL and has to be read alongside the orange bars.

public can contribute with systems, surveys, research and measurement equipment with low-cost sensors and analysis tools. Likewise, the development of air governance criteria that include the affected community will allow concrete actions to be generated for the reduction of pollutants and self-management of risk from exposure to contaminated environments (Wan et al., 2020). In this way, we consider that it is possible to socialize and involve citizens in air quality monitoring, to empower them and educate them regarding the effects and characteristics of air pollution. This can be achieved by disseminating the results at events that include several actors involved in air governance such as the academia, governmental authorities and citizen groups.

4. Conclusions

In the city of Bogotá, PM_{2.5} is the most dangerous pollutant, due to its concentration exceeding daily and annual limits, alongside its hourly peaks (Fig. 3). 2019 had the highest number of alerts concerning air quality in the city, which suggests a negative impact on human health. This highlights the need of implementing a functioning preventive system. For this reason, this work focuses on the creation of a preventive EAS. In order to determine the best predictive models, three machine learning techniques (SVM, LSTM, and 1D-BDLM) are compared with the evaluation of 182 days by means of 9 statistical parameters. This evaluation led to the conclusion that the 1D-BDLM produces the most precise simulations and is able to predict the behavior, magnitude and air quality alarms in an effective manner, without producing false alarms.

The alert system, thus, incorporates a 1D-BDLM that accounts for data uncertainty through the Monte Carlo model and is capable of predicting the risk for each population group. Furthermore, a protocol is designed, using these models as the main input, which activates 24 h before a pollution event. The protocol distinguishes the level of alert (e.g., yellow, orange) and the type of population (e.g., vulnerable groups) at risk, with measures focusing on the mitigation of pollution and the reduction in population risk. To decrease concentrations, restrictions on vehicle traffic in specific zones of the city or, if necessary, in the entire city, are suggested. In relation to stationary sources, the implementation of monitoring measures is proposed, in order to identify the most polluting factories and to (partially or completely) restrict their operation during a specific period of time (e.g., in the peak of concentration levels). Concerning population risk, the protocol seeks to reduce the exposure time of population groups, by avoiding outdoor activities and through the use of protective gear (e.g., masks).

Based on what has been stated, we can conclude that the 1D-BDLM (the most precise model) integrated into the Monte Carlo model is capable of grasping the variability intrinsic to the nature of the data of each station. For example, S7 station has a high variability due to the low number of data and the fact that it does not behave as any statistical distribution. Nonetheless, the model has high accuracy, with an uncertainty of $\approx 7 \pm 4\%$ (Figs. 4–5) in relation to risk prediction, and can establish that the population groups most impacted are adult women (30–65 years) and younger men (12–29 years), due to the fact that these are the groups with the largest population in the city. It also suggests that vulnerable groups (older people, children, and infants) are not at the highest risk but are possibly the most prone to develop serious diseases caused by PM. In addition, it is clear that the protocol must have a preventive approach that starts with the mitigation of the contaminant and a decrease in the population risk, as this could lead to a reduction in the number of people that may suffer PM-related diseases and a reduction in the correlative costs. Accordingly, this alert system (the models and protocol) can be potentially used as a tool of air quality management in cities with PM-related risks.

For future work, it is important to make major efforts in the development of a reliable emission inventory database for the city of Bogotá, allowing the incorporation of the WRF-CHEM model to the EAS, which could aid in the creation of model ensembles, the evaluation of scenarios and the study of the fundamental behavior of the pollutants, something

essential in policy-making (Sokhi et al., 2021). It is also important to test more ANN structures to continue improving the results, especially in cases where steeper changes are presented, or when very anomalous pollutant behavior occurs. For example, the inclusion of a multi-input layer could, in principle, increase the precision of the model. Likewise, the coupling of WRF-CHEM model outputs with ANN can not only better account for meso/regional scale interactions of the atmosphere, but also assess the local behavior of the pollution captured by the networks. In addition, the inclusion of more methods (e.g., BenMAP, Air pollution Social Impact Using Regression -EASIUR-, Intervention Model for Air Pollution -InMAP-) that make the risk assessment calculation more robust are necessary, in order to include ensembles in both risk and air quality models to reduce the uncertainty of the results as much as possible and also to account for the economic impacts associated with PM_{2.5} concentrations.

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CRediT authorship contribution statement

Nathalia Celis and Alejandro Casallas: Conceptualization, Data Curation, Methodology, Software, Validation, Formal Analysis, Visualization, Writing - Original Draft. **Ellie Anne López-Barrera:** Conceptualization, Formal Analysis, Writing - Original Draft. **Hermes Martínez and Carlos A Peña Rincón:** Software, Validation. **Ricardo Arenas:** Formal Analysis, Writing - Original Draft. **Camilo Ferro:** Data Curation, Software, Validation, Formal Analysis.

Declaration of Competing Interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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Appendix A. Supporting information

Supplementary data associated with this article can be found in the online version at [doi:10.1016/j.envsci.2021.10.030](https://doi.org/10.1016/j.envsci.2021.10.030).

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